Frame-Level Features Conveying Phonetic Information for Language and Speaker Recognition

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1 Introduction

- 2 Phone Log-Likelihood Ratio Features
- O PLLR Dimensionality Reduction
- 4 PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work

The Task Datasets Structure of Recognition Systems Feature Extraction Baseline Acoustic System Baseline Phonotactic System Calibration and Fusion Evaluation Measures

1 Introduction

- 2 Phone Log-Likelihood Ratio Features
- 3 PLLR Dimensionality Reduction
- PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work



The Task

Datasets Structure of Recognition Systems Feature Extraction Baseline Acoustic System Baseline Phonotactic System Calibration and Fusion Evaluation Measures

The Task

Spoken language recognition is a pattern recognition task that consists of recognizing the language spoken in an utterance by computational means

The main **complexity** of language recognition tasks comes from dealing with undesired variabilities present in the utterances due to several factors: **channel variabilities**

Extracting informative features robust against those variabilities or designing modeling techniques capable of patterning after the desired variabilities, while discarding the noisy ones, are the main focus of research in the task



The Task

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Applications

The possible applications include, among others:

- Phone service automation
- Phone call filtering
- Search and indexing of audiovisual resources
- Product customization
- Intelligence
- Forensics
- Speech preprocessing in multilingual dialog systems
- Speech preprocessing for suitable model/dictionary selection in data recovery systems
- Security



The Task

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Evolution

Applications becoming more common in the technology surrounding us, thanks to the great human effort put on it in the last decades which has promoted the evolution of SLR systems.

Two main factors have enabled this evolution:

- Growth in computational power
- The increasing amount of available data



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Datasets

NIST Datasets Starting on 1996 and held every two years from 2003 to 2011: Narrow band (8kHz) signals. Mainly conversational telephone speech. Evaluations for 3s, 10s and **30s** speech segments

- NIST 2007 LRE: 14 target languages
- NIST 2009 LRE: 23 target languages, radio broadcasts included as resources (only telephone bandwidth speech)
- **NIST 2011 LRE:** Focused on pairwise language detection task, 24 target languages



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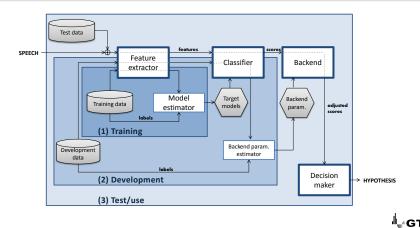
KALAKA-2: Extension of KALAKA. Wide-band TV broadcast speech signals downsampled to (single channel) 16kHz. 6 target languages. Two main evaluation tasks: clean and noisy speech

RATS: Designed to perform SLR in challenging scenarios, focusing on noisy environments. Data for 5 target languages, retransmitted through 8 different communication channels



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Structure of Recognition Systems

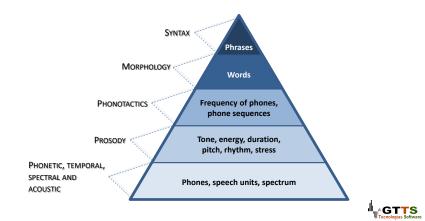


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Introduction

Phone Log-Likelihood Ratio Features PLLR Dimensionality Reduction PLLR Projection PLLRs on Speaker Recognition Conclusions and Future Work The Task Datasets Structure of Recognition Systems Feature Extraction Baseline Acoustic System Baseline Phonotactic System Calibration and Fusion Evaluation Measures

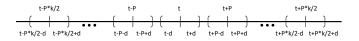
Feature Extraction



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Acoustic Features

- Mel Frequency Cepstral Coefficients (MFCC): frame level features based on Mel scale of frequency
- Shifted Delta Cepstrum (SDC): characterize the language by the evolution of local variations of the spectrum around the analysis window, are specified by four parameters: N-d-P-k





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Baseline acoustic system

- Features are used to train a Gaussian Mixture Model (GMM), that is used as Universal Background Model (UBM)
- Acoustic approaches: MAP-GMM, eigenchannel compensation
- **i-vectors**: The i-vector approach maps high-dimensional input data to a low-dimensional feature vector, hypothetically maintaining most of the relevant information



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i-vector system

Under the i-vector modeling assumption, an utterance GMM supervector (stacking the means of a GMM which is estimated by MAP adaptation of the UBM to the input utterance) is defined as:

$$\mathbf{M} = \mathbf{m} + \mathbf{T}\mathbf{w} \tag{1}$$

- m is the utterance independent mean supervector
- T is the total variability matrix (a low-rank rectangular matrix)
- **w** is the so called *i-vector*, a normally distributed low-dimensional latent vector
- **M** is assumed to be normally distributed with mean **m** and covariance **TT**'
- The latent vector **w** can be estimated from its posterior distribution conditioned to the Baum-Welch statistics



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- Generative modeling approach for i-vectors (each language modeled by a single Gaussian distribution)
- i-vectors classified using Logistic Regression
- i-vectors used to train Neural Network Classifiers



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High level features

Most common representations are based on the information provided by **phone decoders**

- Large amount of labeled data to train the models for each of the phones of their **phonetic inventory**
- Rely on different features: MFCCs, PLPs, etc. Usually augmented to obtain information for larger temporal contexts
- Input frames are scored with regard to the trained phonetic units of the phonetic inventory. Different modelings: GMMs, HMMs, NNs, Hybrid models



The Task Datasets Structure of Recognition Systems Feature Extraction Baseline Acoustic System Baseline Phonotactic System Calibration and Fusion Evaluation Measures

Phone decoders

• Phonemes usually span several frames. Phone-state posteriors represent shorter units and allow a better acoustic modeling of the speech

Given an input sequence of acoustic observations X, they provide an acoustic posterior probability of each state s (1 < s < S) of each phone model i (1 < i < N) at each frame t, p(i|s; t)



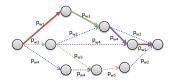
The Task Datasets Structure of Recognition Systems Feature Extraction Baseline Acoustic System Baseline Phonotactic System Calibration and Fusion Evaluation Measures

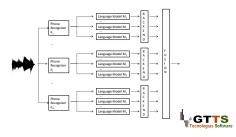
Phonotactic approaches

1-best decoding: the most likely phone sequence **Phone lattices**: perform a summation over phone sequences

PRLM: phone recognition language modeling

PPRLM: parallel phone recognition language modeling, different phonotactic scores combined





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Phone-lattice-SVM approach

- Support Vector Machines, are discriminative models that try to find the boundaries between two classes
- The phone lattice produced by a decoder *i* is stored for each target language *j*, then **feature vectors** are built from **expected counts of phone n-grams**
- A SVM model is estimated on the outputs of the phone decoder *i* for the training dataset, taking *j* as the target language



The Task Datasets Structure of Recognition Systems Feature Extraction Baseline Acoustic System Baseline Phonotactic System Calibration and Fusion Evaluation Measures

Calibration and Fusion

- Score Normalization Helps removing the environmental effects on the score space: Z-Norm, T-Norm, ZT-Norm
- Backend Is a calibration stage that transforms the space of scores to get reliable estimates of the class probabilities, and can map scores to the space of target languages: Generative/Discriminative Gaussian backends, Logistic Regression, etc.
- Fusion Combines scores of several systems to give a final set of calibrated and fused scores



Introduction Phone Log-Likelihood Ratio Features PLLR Dimensionality Reduction PLLR Projection PLLRs on Speaker Recognition Conclusions and Future Work PLTR Projection PLLRs on Speaker Recognition Calibration Measures

Evaluation Measures

Average Cost (C_{avg}): A combination of P_{miss} and P_{fa} pooled across target languages. For closed-set evaluation tasks:

$$C_{\rm avg} = \frac{1}{L} \sum_{i=1}^{L} \left\{ C_{\rm miss} P_{\rm T} P_{\rm miss}(i) + \frac{1}{L-1} \sum_{I_N} C_{\rm fa} (1-P_{\rm T}) P_{\rm fa} (I_T, I_N) \right\}$$
(2)

Average Cost (C_{avg}^{24}) : The primary measure for NIST 2011 LRE, averages the actual cost for the 24 pairs with the highest minimum cost

 $C_{\rm LLR}$: Evaluates system performance globally by means of a single numerical value. It only depends on the scores (not on application dependent parameters), on their ability to discriminate amongst target languages and on how well they are calibrated

Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

1 Introduction

- 2 Phone Log-Likelihood Ratio Features
- 3 PLLR Dimensionality Reduction
- PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work





Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Phone Log-Likelihood Ratio Features

- Phone Log-Likelihood Ratios (PLLR): features for language and speaker recognition
- PLLRs designed to provide acoustic-phonetic information in a sequence of frame-level feature vectors that can be easily plugged into acoustic systems by simply replacing the MFCC-based features



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Phone Log-Likelihood Ratio Features

- Phone decoder including: N phone units, represented by a model of S states. Given an input sequence of acoustic observations X, we assume that the acoustic posterior probability of each state s (1 ≤ s ≤ S) of each phone model i (1 ≤ i ≤ N) at each frame t, p(i|s, t), is output by the phone decoder
- The acoustic posterior probability of a phone unit *i* at each frame *t* can be computed by:

$$p(i|t) = \sum_{\forall s} p(i|s, t) \tag{3}$$

Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Phone Log-Likelihood Ratio Features

In this way, the decoder outputs an *n*-dimensional vector of phone posteriors at each frame *t*: $\mathbf{p}(t) = (p(1|t), p(2|t), \dots, p(n|t))'$

$$\sum_{i=1}^{n} p(i|t) = 1$$
 (4)

$$p(i) \in [0,1]$$
 $i = 1, 2, ..., n.$ (5)

The vector $\mathbf{p}(t)$ defines a certain mixture of phones, the one that, according to the parameters of the phone decoder, best describes the spectral content of the analysis window.

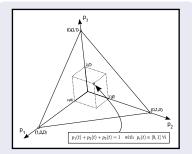
Definition

Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Phone Log-Likelihood Ratio Features

Geometrically, the vector $\mathbf{p}(t)$ can be also interpreted as a point inside an (N - 1)-dimensional region known as *standard* (N - 1)-*simplex*

The standard (N - 1)-simplex $\Delta^{(N-1)}$ is the subset of points in \mathbb{R}^N given by:



Standard 2-simplex defined by phone posteriors in the case of a phone decoder with 3 phonetic units

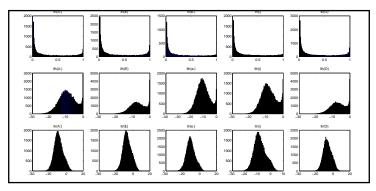
$$\Delta^{(N-1)} = \{(x_0,\ldots,x_{N-1}) \in \mathbb{R}^N \mid \sum_{i=0}^{N-1} x_i = 1 \ \land \ x_i \geq 0 \ orall i\}$$

Frame-Level Features Conveying Phonetic Info. for SLR and SR

Definition

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Phone Log-Likelihood Ratio Features



Distributions of frame-level likelihoods (first row), log-likelihoods (second row) and log-likelihood ratios (third row)

for the Hungarian phones (A:, E, e:, i and O).





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• Assuming a classification task with flat priors, the log-likelihood ratios at each frame *t* can be computed from posterior probabilities as follows:

$$PLLR(i|t) = \log \frac{p(i|t)}{\frac{1}{(N-1)}(1-p(i|t))} \qquad i = 1, ..., N$$
 (6)

- In this way, *n* log-likelihood ratios are computed at each frame *t*, carrying the same information as the *n* phone posteriors, but seemingly featuring Gaussian distributions
- These are the Phone Log-Likelihood Ratio (PLLR) features

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PLLR computation

- Open-software Temporal Patterns Neural Network phone decoders, developed by Brno University of Technology (BUT)
- Decoders for **Czech**, **Hungarian** and **Russian** which include 42, 58 and 49 phonetic units, respectively, plus 3 non-phonetic units
- Non-phonetic units integrated into a single non-phonetic unit: 43 (CZ), 59 (HU) and 50 (RU) PLLR features per frame
- Most results in this presentation using HU phone decoder

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System Configuration

- Voice activity detection performed by removing the feature vectors whose highest PLLR value corresponds to the integrated non-phonetic unit
- Gender independent 1024-mixture GMM UBM
- i-vector approach, 500 dimensional i-vectors



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Backend and Fusion

- The backend setup was **separately optimized for each** dataset
 - NIST 2007, 2009 LRE: ZT-Norm followed by a discriminative Gaussian backend
 - NIST 2011 LRE: no normalization, generative Gaussian backend
 - KALAKA-2: no normalization, no backend
- Discriminative multiclass calibration/fusion estimated on the development set and applied to evaluation scores using the **FoCal toolkit**



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PLLR Extraction Configuration

PLLR extraction configuration optimized on the NIST 2007 LRE dataset

Dynamic coefficients

System	$C_{\mathrm{avg}} imes 100$	$C_{ m LLR}$
PLLR	3.45	0.564
$PLLR+\Delta$	2.66	0.382
$PLLR+\Delta+\Delta\Delta$	3.60	0.506

 $\begin{array}{l} \mbox{Static} + \mbox{first order dynamic} \\ \mbox{coefficients: } \mbox{PLLR}{+}\Delta \rightarrow \\ \mbox{118 features (HU)} \end{array}$

Feature level channel compensation: Feature normalization, feature warping, RASTA filtering.

System	$C_{\mathrm{avg}} imes 100$	$\mathcal{C}_{\mathrm{LLR}}$
PLLR	2.66	0.382
PLLR +FN	2.95	0.436
PLLR +FW	3.21	0.435
PLLR +RASTA	8.67	1.149



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Contrastive Systems

Acoustic feature-based i-vector system

- Concatenation of **MFCC** and **SDC** coefficients under a 7-2-3-7 configuration, 56 dimensional feature vector
- **Same configuration** for the i-vector system as in the PLLR feature-based approach: Voice activity detection, GMM estimation, total variability matrix training, scoring



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Contrastive systems

Phone-lattice-SVM system

- Three phonotactic systems using **BUT TRAPs/NN phone decoders** for Czech, Hungarian and Russian
- Phone posteriors converted to **phone lattices** by **HTK**
- Expected counts of **phone n-grams** computed using the **lattice tool of SRILM**
- **SVM LIBLINEAR classifier**, vectors consisting of expected frequencies of phone *n*-grams (up to *n*=3)



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Overall Results on NIST 2007 LRE

System		$C_{ m avg} imes 100$	$C_{\rm LLR}$	
MFCC-SDC i-vector (a)		2.85	0.407	
HU	Phonotactic PLLR i-vector	(b) (c)	2.08 2.66	0.310 0.382
Fusion	(a)+(b) (a)+(c) (b)+(c) (a)+(b)+(c)		1.08 1.40 1.20 0.82	0.152 0.215 0.166 0.124

Reported results on NIST 2007 LRE



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Overall Results on NIST 2009 LRE

System		$C_{ m avg} imes 100$	$C_{\rm LLR}$	
MFCC-SDC i-vector (a)		2.70	0.535	
HU	Phonotactic PLLR i-vector	(b) (c)	2.49 2.42	0.502 0.505
Fusion	(a)+(b) (a)+(c) (b)+(c) (a)+(b)+(c)		1.67 1.79 1.69 1.48	0.346 0.392 0.357 0.321

▶ Reported results on NIST 2009 LRE



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Overall Results on NIST 2011 LRE

System		$C_{ m avg} imes 100$	$C_{\rm LLR}$	
MFCC-SDC i-vector (a)		5.96	1.088	
HU	Phonotactic PLLR i-vector	(b) (c)	7.15 5.18	1.280 0.982
Fusion	(a)+(b) (a)+(c) (b)+(c) (a)+(b)+(c)		4.34 4.00 4.39 3.63	0.823 0.789 0.829 0.714

▶ Reported results on NIST 2011 LRE



Definition Computation System Configuration Backend and Fusion Development Results Contrastive Systems Results

Results on Albayzin 2010 LRE

			Clean		Nois	y
	System		$C_{\mathrm{avg}} imes 100$	$\mathcal{C}_{\mathrm{LLR}}$	$C_{ m avg} imes 100$	$C_{\rm LLR}$
MFCC-S	DC i-vector	(a)	2.12	0.176	3.95	0.325
HU	Phonotactic	(b)	2.35	0.218	7.28	0.621
	PLLR i-vector	(c)	1.41	0.127	3.17	0.308
	(a)+(b)		1.10	0.106	2.43	0.211
Fusion	(a)+(c)		1.20	0.109	2.65	0.227
	(b)+(c)		1.09	0.092	2.65	0.228
	(a)+(b)+(c)		0.97	0.086	1.86	0.168

▶ Reported results on Albayzin 2010 LRE



Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Introduction

- Phone Log-Likelihood Ratio Features
- 3 PLLR Dimensionality Reduction
- 4 PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work



Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Dimensionality Reduction

- Static + first order dynamic coefficients: PLLR+ $\Delta \rightarrow 86$ features (CZ), 118 features (HU), 100 features (RU)
- Computational problem (for some approaches): PLLR representation larger than common acoustic representations
- **Goal:** To reduce the set of phone units in the PLLR representation
- Several supervised and unsupervised techniques tested



Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Supervised Techniques

For each family, the posterior of each phonetic class was computed by adding the posteriors of the phones included in it, then the log-likelihood ratios were computed

- *Family-R*: The reduced (R) set of phones used by Soufifar et al.¹ to limit the number of n-gram counts (33 phone classes)
- Family-SL: this set is defined by merging Short and Long (SL) phones (31 phone classes)

¹M. Soufifar et al. "Discriminative Classifiers for Phonotactic Language Recognition with i-vectors", *Proc. ICASSP*, Japan, 2012



Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Supervised Techniques

- *Family-MP*: A set of phonemes defined according to phonetic categories following IPA charts, (23 phone classes):
 - Consonants produced with the same Manner and Place (MP) of articulation were merged

		Place of articulation						
		Labial	Alveolar	Post-alveolar	Palatal	Velar	Glottal	
	Nasal	m	n		η			
~ E	Stop	рb	td		сյ	kg		
Manner of articulation	Affricate		ts dz	t∫ d3	¢ç jî*			
cula	Fricative	fv	s z	∫3			h	
Σir	Trill		r					
	Approximant				j			

• Vowels belonging to the same regions in the IPA charts were also merged

Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Supervised Techniques

- Family-M: More generic (14 phone classes)
 - Consonants produced with the same **Manner (M)** of articulation were merged

			Place of articulation						
		Labial	Alveolar	Post-alveolar	Palatal	Velar	Glottal		
	Nasal	m	n		η				
5	Stop	рb	t d		сյ	kg			
Manner of articulation	Affricate		ts dz	t∫ d3	€ç jî*				
	Fricative	fv	s z	∫ 3			h		
Σr	Trill		r						
	Approximant		I		j				

• Vowels belonging to the same regions in the IPA charts were also merged



Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Unsupervised Techniques

- *Correlation*: An iterative clustering algorithm is used. In each step, the algorithm **merges** the closest pair of phones according to the **correlation among the phone posterior probabilities**
- Frequency: The N phones with the highest posterior probabilities overall in the training set are **selected** and used as (reduced) phone set
- PCA was also tested. Since PCA is an orthogonal transformation that is assumed to deal with normally distributed data ranging in $(-\infty, \infty)$, it is not a suitable transformation to be applied on the phone posterior probability space. Instead, PCA is directly applied on the normally distributed PLLR space



Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Comparison of dimensionality Reduction Techniques

HU PLLR System				Dim	$\%C_{\mathrm{avg}}$	$C_{\rm LLR}$
Baseline			59+A	2.86	0.389	
Supervised	Merge Phones	Family	R SL MP M	$33+\Delta$ $31+\Delta$ $23+\Delta$ $14+\Delta$	3.07 3.46 2.98 4.22	0.422 0.467 0.426 0.580
	Merge Phones	(orrelatio		23+Δ	3.76	0.523
Unsupervised	Select Phones	Freque	ncy	23+Δ	3.56	0.480
	PLLR Projection	PCA		23+Δ	2.45	0.333

Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

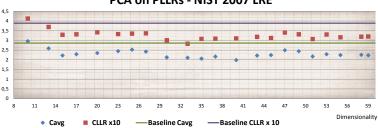
PCA Dimensionality Study

- PCA projection of the features decorrelates the feature space, making the features more suitable for the diagonal covariance GMMs used in the approach
- Search for an **optimal compromise** between the feature vector **size** and the **performance** of the system
- Find the **minimum feature vector size** without high degradation to test the effect of the **Shifted-Delta** transformation over the reduced set of features



PCA Dimensionality Study

PCA Dimensionality Study



Degradation of the systems starts when reducing the features to around 13 dimensions

PCA on PLLRs - NIST 2007 LRE

Techniques Results PCA Dimensionality Study Shifted Delta PLLRs

Shifted Delta PLLRs

SLR performance of an i-vector system based on SD-PLLR features was optimized using different N, P and d values, on the NIST 2007 LRE 30s test set

System	$C_{\rm avg}$	$\mathcal{C}_{\mathrm{LLR}}$
Baseline	2.66	0.382
SD-PLLR 13-2-3-7	1.71	0.260

Performance on the NIST 2011 LRE 30s test set

System	C_{avg}	$\mathcal{C}_{ ext{LLR}}$	$\% C_{\rm avg}^{24}$
Baseline	5.18	0.982	12.12
SD-PLLR 13-2-3-7	4.10	0.826	10.48



PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

Introduction

- Phone Log-Likelihood Ratio Features
- 3 PLLR Dimensionality Reduction
- 4 PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work



PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

PLLR Feature Space

 ${\sf PLLRs}$ address the non-Gaussian nature of phone posteriors for each (one-dimensional) individual phone model

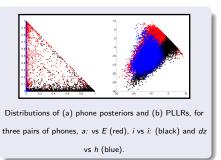
One dimensional distributions

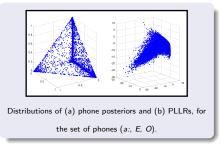
When further analyzing the multidimensional distribution of PLLRs, the seemingly Gaussian distributed features show a strongly bounded distribution



PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

PLLR Feature Space







Introduction Phone Log-Likelihood Ratio Features PLLR Dimensionality Reduction PLLR Projection

PLLRs on Speaker Recognition Conclusions and Future Work PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs



PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

PLLR Feature Space

Phone posterior vector
$$\mathbf{p}(t) = (p(1|t), p(2|t), \dots, p(N|t))'$$

$$PLLR(i|t) = \log \frac{p(i|t)}{(1 - p(i|t))} \qquad i = 1, ..., N$$
(7)

As phone posteriors range in [0,1], PLLRs would seemingly range in $(-\infty,\infty)$

But the constraint among phone posteriors $(\sum_{i=1}^{N} p(i|t) = 1)$ is transferred into the PLLR space.

PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

PLLR Feature Space

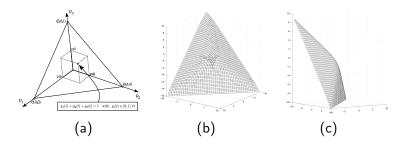
From the simplex (space where the phone posteriors lay) and the PLLR definition, we derive the hyper-surface S where the PLLRs lay:

$$\mathcal{S}^{(N-1)} = \left\{ \mathbf{r} \in \mathbb{R}^N \, \middle| \, \mathcal{G}(\mathbf{r}) = \sum_{i=1}^N \frac{1}{1+e^{-r_i}} - 1 = 0 \right\}$$
(8)

where $\mathcal{G}(\mathbf{r})$ is the implicit hyper-surface function in the PLLR space.

PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

PLLR Feature Space



(a) Standard 2-simplex defined by phone posteriors in the case of a phone decoder with 3 phonetic units. Graphs (b) and (c) show the hyper-surface where PLLRs lie for the case of a phone decoder with 3 phonetic units.

Introduction Phone Log-Likelihood Ratio Features PLLR Dimensionality Reduction PLLR Projection

PLLRs on Speaker Recognition Conclusions and Future Work PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs



PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

PLLR Projection

The hyper-surface ${\cal S}$ is asymptotically perpendicular to the basis of PLLRs, which explains the bounded distributions shown.

Demonstration

To avoid this bounding effect, we propose to project PLLRs into the hyper-plane tangential to the surface at the point where all the posteriors take the same value $p_i = \frac{1}{N}$, that is, the top of the convex surface, where the normal vector is:

$$\mathbf{n}|_{r_i=-\log(N-1)} = \frac{(N-1)}{N\sqrt{N}} \cdot \mathbf{\hat{1}}$$
(9)

where $\mathbf{\hat{1}} = \frac{1}{\sqrt{N}} [1_1, 1_2, ..., 1_N].$

PLLR Feature Space **PLLR Projection** Results Shifted Delta Projected PLLRs

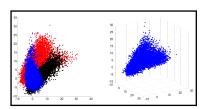
PLLR Projection

In the general case (N dimensions), the kernel (null space) of the desired projection is $\hat{\mathbf{1}}$, then the projection matrix P is given by:

$$P = \mathbb{I} - \hat{\mathbf{i}}' * \hat{\mathbf{i}}$$
(10)

Distribution of the PLLRs shown in previous figures after projecting them into the defined hyper-plane.

Finally, in order to decorrelate the parameters, we apply PCA on the transformed PLLRs $\hfill \hfill \hfi$



PLLR Feature Space PLLR Projection **Results** Shifted Delta Projected PLLRs

Results

PLLR System	$%C_{ m avg}$ (r.i.)	$C_{ m LLR}$ (r.i.)
Baseline 59	2.86	0.389
Projection 59	2.31 (19%)	0.320 (18%)
Projection+PCA 58	2.10 (27%)	0.310 (20%)
PCA 59 58	2.24 (22%)	0.321 (17%)
58	2.26 (21%)	0.319 (18%)

 $%C_{\rm avg}$ and $C_{\rm LLR}$ performance (and relative improvements) for the PLLR i-vector baseline system, and systems using PLLR features on the NIST 2007 LRE primary evaluation task.

PLLR Feature Space PLLR Projection **Results** Shifted Delta Projected PLLRs

Results

Dataset	System		$\%C_{\mathrm{avg}}$	$\mathcal{C}_{\mathrm{LLR}}$	$\% C_{ m avg}^{24}$
	PLLR	(a)	2.42	0.505	-
	PLLR+Projection+PCA	(b)	2.19	0.443	-
2009	Acoustic MFCC	(c)	2.70	0.535	-
LRE	Phonotactic	(d)	2.49	0.502	-
LKE	(c)+(d)		1.67	0.346	-
	(a)+(c)+(d)		1.48	0.321	-
	(b)+(c)+(d)		1.42	0.307	-
	PLLR	(a)	5.18	0.981	12.12
	PLLR+Projection+PCA	(b)	4.30	0.824	11.33
2011	Acoustic MFCC	(c)	5.95	1.088	13.56
LRE	Phonotactic	(d)	7.15	1.280	14.28
LKE	(c)+(d)		4.34	0.823	10.43
	(a)+(c)+(d)		3.63	0.714	9.14
	(b)+(c)+(d)		3.33	0.667	8.91

GTTS Tecnologias Software

PLLR Feature Space PLLR Projection **Results** Shifted Delta Projected PLLRs

PLLRs on RATS

- Data of the RATS program 5 target languages and 10 non-target languages
- Levantine Arabic and Czech phone recognizers, based on a hybrid NN/HMM approach
- Projected PLLRs+*Delta* used to compute 600 dimensional i-vectors
- Two PLLR approaches based on different classifiers
 - Multi-class regularized Logistic Regression
 - Three-layer NN classifiers with 300 neurons in the hidden layer and 6 outputs
- Contrastive Perceptual Linear Prediction and Subspace n-gram Model feature-based systems

PLLR Feature Space PLLR Projection **Results** Shifted Delta Projected PLLRs

PLLRs on RATS

Results with LR - $C_{\rm avg}$ [%]

System	120s	30s	10s	3s
PLP2	7.72	11.69	16.39	23.04
SnGM-LE	5.86	12.28	18.53	26.45
SnGM-CZ	8.59	15.76	20.89	27.95
PLLR-LE	4.56	7.98	12.61	21.48
PLLR-CZ	6.95	10.76	15.13	21.32



PLLR Dimensionality Reduction PLLR Projection PLLRs on Speaker Recognition Conclusions and Future Work

Results

FO / 3

PLLRs on RATS

Results with NN - $\mathcal{C}_{\mathrm{avg}}$ [%]						
Sys	stem	120s	30s	10s	3s	
1	PLP2	7.21	9.21	12.43	18.58	
2	SnGM-LE	5.53	9.34	15.61	22.76	
3	SnGM-CZ	7.23	10.46	15.38	24.05	
4	PLLR-LE	5.37	7.31	11.46	17.63	
5	PLLR-CZ	5.81	8.83	12.30	19.52	
Fus	sions	120s	30s	10s	3s	
4+	5	5.19	6.79	10.14	16.04	
1 +	4	5.80	6.43	8.69	15.37	
2+	4	5.12	6.61	10.48	16.93	
3+	5	5.74	8.33	11.28	18.11	
1 +	2+4	5.38	6.31	8.53	14.90	
1 +	4+5	5.29	6.43	8.71	14.65	
1+	2+3+4+5	5.59	6.21	8.75	14.37	

62 / 76

Tecnologias Software

PLLR Feature Space PLLR Projection Results Shifted Delta Projected PLLRs

Shifted Delta Projected PLLRs

Results on the NIST 2007 LRE dataset

PLLR System	$\%C_{ m avg}$	$\mathcal{C}_{\mathrm{LLR}}$
Projection + PCA 58	2.10	0.310
Projection + PCA 13	2.43	0.330
$Projection + PCA \ 13 + SD$	1.52	0.225

Results on the NIST 2011 LRE dataset

PLLR System	$%C_{\mathrm{avg}}$	$\mathcal{C}_{\mathrm{LLR}}$	$\% C_{\rm avg}^{24}$
Projection + PCA 58	4.30	0.824	11.33
$Projection + PCA \ 13 + SD$	4.84	0.916	12.49
$Projection + PCA \ 15 + SD$	4.39	0.833	11.26
$Projection + PCA \ 17 + SD$	3.80	0.756	9.52

Contrastive Acoustic System Datasets Evaluation Measures Results

Introduction

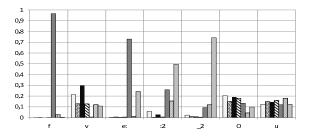
- Phone Log-Likelihood Ratio Features
- 3 PLLR Dimensionality Reduction
- 4 PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work





Contrastive Acoustic System Datasets Evaluation Measures Results

PLLRs on Speaker Recognition



Normalized average posteriors $\hat{p}(i|s)$ of seven Hungarian phones on the same utterance of the TIMIT dataset for 7 different speakers. The subset of phones represents fricative labiodental consonants (f and v) and a subset of vowels (e:, :2, _2, O, u), as defined in the International Phonetic Alphabet.

Contrastive Acoustic System Datasets Evaluation Measures Results

PLLRs on Speaker Recognition

- $\mathbf{PLLR} + \Delta$ configuration found also the best parameterization
- i-vector Gaussian PLDA Approach
- Gender dependent 1024-mixture UBMs
- Gender dependent Total Variability matrices
- i-vector dimensionality set to 500

Contrastive Acoustic System Datasets Evaluation Measures Results

Acoustic Feature-Based System

- 13 MFCC coefficients, including the zero (energy) coefficient
- Cepstral Mean Subtraction and Feature Warping
- Feature vector augmented with first and second order deltas: 39-dimensional feature vector



Contrastive Acoustic System Datasets Evaluation Measures Results

Datasets

NIST SRE Datasets

- Annual evaluations from 1996 to 2006, biannual ever since. Conversational speech data from the Mixer Corpora. Gender dependent, text independent datasets
- Training resources cover several conditions: telephone conversation excerpts, two-channel conversations, interview segments, summed-channel conversations
- Test conditions also covered several conditions



Contrastive Acoustic System Datasets Evaluation Measures Results

Evaluation Measures

Detection Cost Function (DCF)

$$DCF = \frac{C_{\text{miss}}P_{\text{T}}P_{\text{miss}(i)} + \sum C_{\text{fa}}(1 - P_{\text{T}})P_{\text{fa}}(L_{T}, L_{N})}{\min\{C_{\text{miss}}P_{T}, C_{\text{fa}}(1 - P_{T})\}}$$
(11)

EER

This measure reports system performance at the operation point for which the false alarm error rate ($P_{\rm fa}$) is equal to the miss error rate ($P_{\rm miss}$)



Contrastive Acoustic System Datasets Evaluation Measures Results

Results on the NIST 2010 SRE

	Condition	System	EER	MinDCF	ActDCF
(1)	Interview same microphone in training and test	MFCC PLLR+Δ Fusion	1.86 4.05 1.40	0.417 0.653 0.363	0.439 0.854 0.367
(2)	Interview different microphone in training and test	MFCC PLLR+Δ Fusion	2.99 6.39 2.36	0.562 0.804 0.492	0.633 0.819 0.553
(3)	Interview training telephone test	MFCC PLLR+Δ Fusion	3.63 9.20 3.25	0.625 0.862 0.522	0.848 0.978 0.874
(4)	Interview training telephone test rec. over microphone	$\begin{array}{c} MFCC \\ PLLR+\Delta \\ Fusion \end{array}$	1.71 5.52 1.69	0.443 0.690 0.372	0.475 0.703 0.406
(5)	Telephone in training and test	MFCC PLLR+Δ Fusion	4.64 8.41 4.29	0.600 0.848 0.560	0.712 0.869 0.688



Contrastive Acoustic System Datasets Evaluation Measures Results

Results on the NIST 2012 SRE

Condition		System	EER	MinDCF	ActDCF
(2)	Telephone with No Added Noise	MFCC PLLR+Δ	1.77 3.12	0.272 0.419	0.290 0.440
		Fusion	5.12 1.39	0.419 0.215	0.440 0.246
(5)	Telephone Recorded in Noise	MFCC	1.93	0.260	0.294
		$PLLR+\Delta$	3.72	0.449	0.481
		Fusion	1.64	0.219	0.283



Conclusions Future Work

Introduction

- Phone Log-Likelihood Ratio Features
- 3 PLLR Dimensionality Reduction
- PLLR Projection
- 5 PLLRs on Speaker Recognition
- 6 Conclusions and Future Work





Conclusions

Summary

- **PLLR** feature-based systems improve Spoken Language Recognition performance under the i-vector approach, even outperforming acoustic and/or phonotactic approaches
- The system **contributes in fusions**, providing complementary information to both acoustic and phonotactic systems
- PLLR systems built on different decoders can be fused to get significant gains in performance
- Good performance of the system under **noisy conditions**
- PLLR feature vector dimensionality can be significantly reduced attaining almost the same performance

Conclusions Future Work

Summary

- Applying **PCA** in the PLLR feature space not only **reduces the computational cost**, but also **improves system performance**
- PLLRs can be projected to get unbounded distributions which enhances the information retrieved by the system
- On Speaker Recognition, **PLLR** feature-based system provides significant improvements in fusions
- PLLRs provide a suitable way of conveying complementary acoustic-phonetic information for language and speaker recognition



Conclusions Future Work

Current & Future Work

- Test the approach under different modeling approaches
- Further analyze performance of PLLRs on short signals and noisy environments
- Use other phone decoders or combinations of their outputs to compute PLLRs
- Study and optimize PLLRs for speaker recognition
- PLLRs for text-dependent speaker recognition



Conclusions Future Work

Thank you!





Conclusions Future Work

Reported results on the primary task of the NIST 2007 LRE

Approach	Model	EER	C_{avg} $ imes$ 100
	GMM-MMI [Torres et.al. 08]	-	2.10
Acoustic	GSV-SVM [Torres et.al. 08]	-	1.92
	Discriminative GMM-MAP [Brummer et.al. 09]	-	1.74
	HU, Phone-SVM, lattices [Tong et.al. 10]	1.84	-
Phonotactic	HU, Phone-SVM, lattices [Richardson et.al. 08]	2.40	-
	EN, Phone-SVM, lattices [Richardson et.al. 08]	1.80	-
PLLR	HU, i-vector, generative		2.66
	2 acoustic subsystems [Torres et.al. 08]	-	1.55
	2 phonotactic subsystems [Torres et.al. 08]	-	1.55
Fusions	3 phonotactic subsystems [BenZeghiba et.al. 12]	-	0.90
	4 subsystems [Torres et.al. 08]	0.93	0.97
	acoustic+phonotactic+PLLR	0.80	0.82



77 / 76

Conclusions Future Work

Reported results on the primary task of the NIST 2009 LRE

Approach	Model	EER	$C_{avg} \times 100$
	GMM-MMI [DehakN et. al. 11]	2.30	-
	SVM-GSV [Torres et. al. 09]	-	2.30
Acoustic	JFA [Jancik et. al. 10]	-	2.02
Acoustic	i-vector (LDA+WCCN) [DehakN et. al. 11]	2.40	-
	i-vector, generative [Martinez et. al. 12]	-	3.09
	i-vector (Logistic reg.) [Plchot et. al. 12]	-	2.35
	EN, Phone-SVM [Torres et. al. 09]	-	2.34
Phonotactic	HU, Phone-SVM [Mikolov et. al. 10]	-	3.85
	RU, Phone-SVM [Mikolov et. al. 10]	-	3.03
PLLR	PLLR HU, i-vector, generative		2.42
	2 acoustic subsystems [Torres et. al. 09]	-	2.00
	2 acoustic subsystems [Plchot et. al. 12]	-	1.78
	3 phonotactic subsystems [Mikolov10]	-	2.39
Fusions	3 phonotactic subsystems [BenZeghiba et. al. 12]	-	1.99
	3 subsystems [Torres et. al. 09]	-	1.64
	36 subsystems [Castaldo et. al. 10]	-	1.16
	acoustic+phonotactic+PLLR	1.47	1.48

Mireia Diez





Conclusions Future Work

Reported results on the primary task of the NIST 2011 LRE

Approach	Model	$C_{avg} \times 100$	$C_{avg}^{24} \times 100$	
Арргоаст	Model	$C_{avg} \times 100$	min	actual
	i-vector (LDA) [Singer et. al. 12]	4.15	-	8.90
Acoustic	i-vector (HLDA) [Brummer et. al. 12]	-	-	10.35
	GMM-SVM [HuaiYou et. al. 12]	-	10.41	-
Phonotactic	RU, PCA [Brummer et. al. 12]	-	-	14.32
FIIOHOLACLIC	HU, <i>n</i> -gram i-vector [Brummer et. al. 12]	-	-	15.42
PLLR	HU, i-vector, generative	5.18	9.83	12.12
	5 subsystems [Singer et. al. 12]	3.30	-	7.00
	8 subsystems [Rodriguez et. al. 12]	3.35	5.09	7.64
Fusions	3 subsystems [Brummer et. al. 12]	-	-	8.47
	3 subsystems [HuaiYou et. al. 12]	-	9.02	-
	acoustic+phonotactic+PLLR	3.63	6.68	9.14



Conclusions Future Work

Reported results on the primary task: Albayzin 2010 LRE

Condition	Approach	Model	C_{avg} $ imes$ 100
	Acoustic	JFA [Martinez et.al. 11]	1.86
		GMM-MMI [Martinez et.al. 11]	4.33
	Phonotactic	HU, Phone-ML [Martinez et.al. 11]	4.41
		EN, Phone-ML [Rodriguez et.al. 11]	3.26
Clean	PLLR	HU, i-vector, generative	1.41
	Fusions	8 subsystems [Martinez et.al. 11]	1.84
		5 subsystems [Rodriguez et.al. 12]	1.77
		2 subsystems [Abad et.al. 10]	1.81
		acoustic+phonotactic+PLLR	0.97
		5 subsystems [Rodriguez et.al. 12]	3.90
Noisy	Fusions	2 subsystems [Abad et.al. 10]	2.53
		acoustic+phonotactic+PLLR	1.86



Conclusions Future Work

Results Using Multiple Decoders NIST 2011 LRE

PLLR Syste	$\%C_{\mathrm{avg}}$	C _{LLR}	%C_{avg}^{24}	
Baseline	$\begin{array}{c} CZ (43+\Delta) \\ HU (59+\Delta) \\ RU (50+\Delta) \\ \mathbf{CZ+HU+RU} \end{array}$	5.31 5.18 4.70 3.79	0.978 0.982 0.898 0.720	12.46 12.12 11.27 9.10
Family-MP	$\begin{array}{c} CZ (25+\Delta) \\ HU (23+\Delta) \\ RU (21+\Delta) \\ \mathbf{CZ+HU+RU} \end{array}$	5.53 5.40 5.13 3.82	1.054 1.015 0.961 0.693	13.62 12.64 11.57 9.79
PCA	$\begin{array}{c} CZ (25+\Delta) \\ HU (23+\Delta) \\ RU (21+\Delta) \\ \mathbf{CZ+HU+RU} \end{array}$	4.46 4.48 4.20 3.21	0.855 0.877 0.803 0.634	11.20 10.88 11.01 8.45

Conclusions Future Work

PLLR feature space

The hyper-surface S is asymptotically perpendicular to the basis of PLLRs, which explains the bounded distributions shown. The normal vector to the hyper-surface S is:

$$\mathbf{n} = \nabla \mathcal{G}(\mathbf{r}) \tag{12}$$

where each component n_i of **n** is given by:

$$n_i = \frac{e^{r_i}}{(1 + e^{r_i})^2} \tag{13}$$

Conclusions Future Work

PLLR feature space

Let us consider the case in which a subset of phones $\mathcal{I} \subset \{1, 2, ..., N\}$ accounts for most of the probability mass, that is, $\sum_{\forall i \in \mathcal{I}} p_i = 1 - \epsilon$. As these phones tend to take all the probability mass, it follows that $\sum_{\forall i \in \mathcal{I}} p_i \rightarrow 1$ and $\epsilon = \sum_{\forall i \notin \mathcal{I}} p_i \rightarrow 0$ (therefore, $r_i \rightarrow -\infty \ \forall i \notin \mathcal{I}$). Accordingly, for the normal vector **n** it holds:

$$\lim_{\epsilon \to 0} n_i = 0 \qquad \forall i \notin \mathcal{I}$$
(14)

That is, the normal vector tends to lie in the subspace Q where the set of phones \mathcal{I} are confined. Hence, the surface is asymptotically perpendicular to any basis defined on Q.

Back